

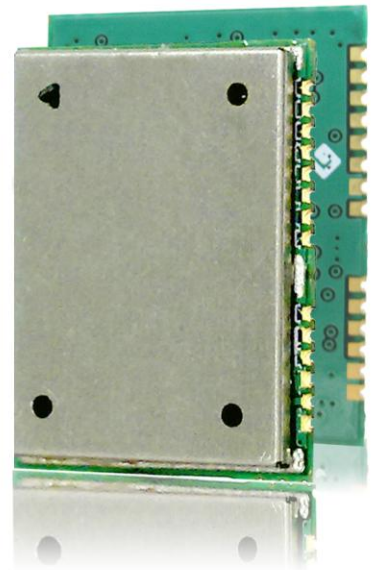


L10-C

Quectel GPS Engine

Hardware Design

L10-C_HD_V1.1



Document Title	L10-C Hardware Design
Revision	1.1
Date	2011-06-27
Status	Release
Document Control ID	L10-C_HD_V1.1

General Notes

Quectel offers this information as a service to its customers, to support application and engineering efforts that use the products designed by Quectel. The information provided is based upon requirements specifically provided for customers of Quectel. Quectel has not undertaken any independent search for additional information, relevant to any information that may be in the customer's possession. Furthermore, system validation of this product designed by Quectel within a larger electronic system remains the responsibility of the customer or the customer's system integrator. All specifications supplied herein are subject to change.

Copyright

This document contains proprietary technical information of Quectel Co., Ltd. Copying of this document, distribution to others, and communication of the contents thereof, are forbidden without permission. Offenders are liable to the payment of damages. All rights are reserved in the event of a patent grant or registration of a utility model or design. All specifications supplied herein are subject to change without notice at any time.

Copyright © Quectel Wireless Solutions Co., Ltd. 2011

Contents

0 Revision history	4
1 Introduction.....	5
1.1 Related documents	5
1.2 Terms and abbreviations.....	5
2 Product concept.....	7
2.1 Key features	7
2.2 Functional diagram.....	8
2.3 Evaluation board	9
2.4 Assisted GPS.....	9
2.5 Protocol	9
3 Application interface.....	10
3.1 Pin description.....	10
3.2 Operating modes	12
3.3 Power supply.....	12
3.4 Turn on and Turn off.....	12
3.4.1 Turn on	12
3.4.2 Turn off.....	14
3.5 Power saving	14
3.5.1 Enter standby mode	14
3.5.2 Exit from standby mode	14
3.6 RTC backup	14
3.7 UART interface.....	16
3.8 USB interface.....	18
3.9 Software upgrade.....	19
3.10 EXTINT0	19
4 Antenna interface	20
4.1 Antenna	20
4.2 Antenna supply	20
4.2.1 Passive antenna.....	20
4.2.2 Active antenna.....	21
5 Electrical, reliability and radio characteristics	23
5.1 PIN assignment of the module	23
5.2 Absolute maximum ratings.....	24
5.3 Operating conditions	24
5.4 Current consumption	25
5.5 Electro-static discharge	25
5.6 Reliability test	26
6 Mechanics	27
6.1 Mechanical dimensions of the module.....	27
6.2 Footprint of recommendation.....	29
6.3 Top view of the module	30

6.4 Bottom view of the module	30
-------------------------------------	----

Table Index

Table 1: Related documents	5
Table 2: Terms and abbreviations.....	5
Table 3: Module key features	7
Table 4: The module supports protocol.....	9
Table 5: Pin description.....	10
Table 6: Overview of operating modes	12
Table 7: Pin definition of the V_BCKP pin.....	15
Table 8: Pin definition of the UART interfaces.....	16
Table 9: Pin definition of USB interface.....	18
Table 10: Pin definition of the EXTINT0	19
Table 11: Antenna specification for L10-C module	20
Table 12: L10-C pin assignment	23
Table 13: Absolute maximum ratings	24
Table 14: The module power supply ratings	24
Table 15: The module current consumption (passive antenna).....	25
Table 16: The ESD endurance table (Temperature: 25°C, Humidity: 45 %).....	26
Table 17: Reliability test	26

Figure Index

Figure 1: Module functional diagram	8
Figure 2: Reference reset circuit using OC circuit.....	13
Figure 3: Reference reset circuit using button	13
Figure 4: Timing of restart system	14
Figure 5: RTC supply from non-chargeable battery or capacitor.....	15
Figure 6: Reference charging circuit for chargeable battery	15
Figure 7: Seiko XH414H-IV01E charge characteristic.....	16
Figure 8: Connection of UART port	17
Figure 9: RS-232 level shift circuit.....	18
Figure 10: USB interface circuit	19
Figure 11: Reference design for passive antenna.....	21
Figure 12: Active antenna biasing.....	21
Figure 13: Active antenna using VCC_RF as power supply.....	22
Figure 14: Active antenna with external LDO	22
Figure 15: L10-C Top view and Side dimensions (Unit:mm)	27
Figure 16: L10-C Bottom dimensions (Unit:mm)	28
Figure 17: PAD Bottom dimensions (Unit:mm)	28
Figure 18: Footprint of recommendation (Unit: mm)	29
Figure 19: Top view of the module	30
Figure 20: Bottom view of the module	30

0. Revision history

Revision	Date	Author	Description of change
1.0	2011-06-02	Layne YE	Initial
1.1	2011-06-27	Layne YE	<ol style="list-style-type: none">1) Deleted the note of module current consumption in different mode in chapter 5.42) Added the note of the module current consumption in standby mode when the active antenna use VCC_RF as power supply in Figure13

1. Introduction

This document defines and specifies L10-C GPS module. It describes L10-C hardware interface and its external application reference circuits, mechanical size and air interface.

This document can help you quickly understand module interface specifications, electrical and mechanical details. With the help of this document and other application notes, you can use L10-C module to design and set up your applications quickly.

1.1 Related documents

Table 1: Related documents

SN	Document name	Remark
[1]	L10-C_HD_AN	L10-C Hardware Design Application Notes
[2]	L10_EVB_UGD*	L10 EVB User Guide
[3]	L10-C_GPS_Protocol	L10-C GPS Protocol Specification

** L10-C module uses the same EVB as L10 module. For the use of L10-C EVB, please refer to the L10_EVB_UGD document.*

1.2 Terms and abbreviations

Table 2: Terms and abbreviations

Abbreviation	Description
BEE	Broadcast Ephemeris Extension
EMC	Electromagnetic Compatibility
ESD	Electrostatic Discharge
EPO	Extended Prediction Orbit
EGNOS,	European Geostationary Navigation Overlay Service
GPS	Global Positioning System
GNSS	Global Navigation Satellite System
GGA	GPS Fix Data
GLL	Geographic Position – Latitude/Longitude
GSA	GNSS DOP and Active Satellites
GSV	GNSS Satellites in View
HDOP	Horizontal Dilution of Precision
IC	Integrated Circuit

I/O	Input/Output
Kbps	Kilo Bits Per Second
LNA	Low Noise Amplifier
MSAS	Multi-Functional Satellite Augmentation System
NMEA	National Marine Electronics Association
OMA	Open Mobile Alliance
PDOP	Position Dilution of Precision
PMTK	MTK Private Protocol
RMC	Recommended Minimum Specific GNSS Data
RTCM	Radio Technical Commission for Maritime Services
SBAS	Satellite-based Augmentation System
SUPL	Secure User Plane Location
SAW	Surface Acoustic Wave
USB	Universal Serial Bus
UART	Universal Asynchronous Receiver & Transmitter
VDOP	Vertical Dilution of Precision
VTG	Course over Ground and Ground Speed, Horizontal Course and Horizontal Velocity
WAAS	Wide Area Augmentation System
ZDA	Time & Date
Inorm	Normal Current
Imax	Maximum Load Current
Vmax	Maximum Voltage Value
Vnorm	Normal Voltage Value
Vmin	Minimum Voltage Value
VIHmax	Maximum Input High Level Voltage Value
VIHmin	Minimum Input High Level Voltage Value
VILmax	Maximum Input Low Level Voltage Value
VILmin	Minimum Input Low Level Voltage Value
VImax	Absolute Maximum Input Voltage Value
VImin	Absolute Minimum Input Voltage Value
VOHmax	Maximum Output High Level Voltage Value
VOHmin	Minimum Output High Level Voltage Value
VOLmax	Maximum Output Low Level Voltage Value
VOLmin	Minimum Output Low Level Voltage Value

2. Product concept

L10-C GPS module brings the high performance of the MTK positioning engine conforming to the industrial standard. The module supports 210 PRN channels. With 66 search channels and 22 simultaneous tracking channels, it acquires and tracks satellites in the shortest time even at very low signal level. This versatile, stand-alone receiver combines an extensive array of features with flexible connectivity options. The embedded FLASH memory provides capacity for storing user-specific configuration settings and allows for future updates. L10-C advanced jamming suppression mechanism and innovative RF architecture provide a high level of immunity for jamming, ensuring maximum GPS performance. The module supports location, navigation and industrial applications including autonomous GPS C/A, SBAS (including WAAS, EGNOS, and MSAS) and AGPS.

L10-C module is an SMD type module with the compact 22.4mm x 17.0mm x 3.0 mm form factor, which can be embedded in users' applications through 28-pin pads. It provides all hardware interfaces between the module and customer's board.

- The UART port can help to develop customer's application easily.
- The USB port is available for faster data transmission and more flexible.
- The antenna interface supports passive and active antenna.

The module is fully RoHS compliant to EU regulation.

2.1 Key features

Table 3: Module key features

Feature	Implementation
Power supply	Single supply voltage: 3.0V – 4.3V typical : 3.3V
Power consumption (passive antenna)	<ul style="list-style-type: none"> ● Acquisition 43mA ● Tracking 35mA ● Standby 2mA
Receiver Type	<ul style="list-style-type: none"> ● GPS L1 1575.42MHz C/A Code ● 66 search channels, 22 simultaneous tracking channels
Sensitivity (passive antenna)	<ul style="list-style-type: none"> ● Cold Start (Autonomous) -145 dBm ● Reacquisition -157 dBm ● Tracking -162 dBm
Time-To-First-Fix	<ul style="list-style-type: none"> ● Cold Start (Autonomous) 35s average ● Warm Start (Autonomous) 35s average ● Hot Start (Autonomous) <1.2 s ● SUPL 5 ~ 10 s
Position Accuracy	<ul style="list-style-type: none"> ● 1.25 m CEP
Max Update Rate	<ul style="list-style-type: none"> ● 5Hz
Accuracy of 1PPS Signal	<ul style="list-style-type: none"> ● Typical accuracy 61 ns

Feature	Implementation
	<ul style="list-style-type: none"> Time pulse adjustable from 1ms to 999ms, default 100ms
Velocity Accuracy	<ul style="list-style-type: none"> 0.1 m/s
Acceleration Accuracy	<ul style="list-style-type: none"> 0.1 m/s²
Dynamic Performance	<ul style="list-style-type: none"> Maximum Altitude 18,000 m Maximum Velocity 515 m/s Acceleration 4 G
UART Port	UART Port: <ul style="list-style-type: none"> Two lines TXD1 and RXD1 UART Port supports baud rate from 4800bps to 115200bps. UART Port is used for NMEA output or input , PMTK private messages input and firmware upgrade
USB Port	<ul style="list-style-type: none"> Support USB 2.0 full-speed compatible USB Port is used for NMEA outputting or inputting , PMTK private messages inputting and firmware upgrade
Temperature range	<ul style="list-style-type: none"> Normal operation: -40 °C ~ +85 °C Storage temperature: -45 °C ~ +125 °C
Physical Characteristics	Size: 22.4±0.15 x 17±0.15 x 3.0±0.1mm Weight: about 2.2g
Firmware Upgrade	Firmware upgrade over UART port or USB port

2.2 Functional diagram

The following figure shows a block diagram of L10-C module.

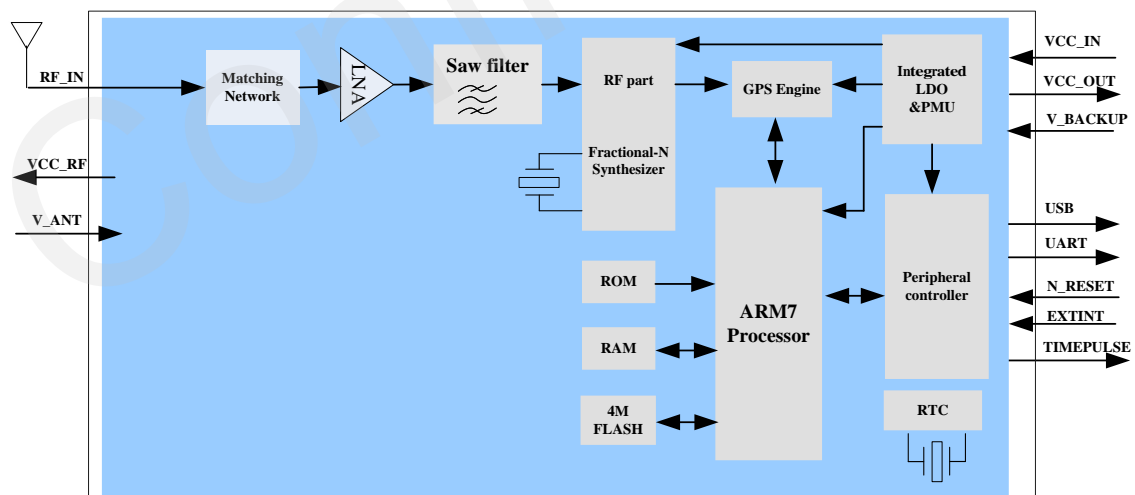


Figure 1: Module functional diagram

2.3 Evaluation board

In order to help customer to develop applications with L10-C, Quectel supplies an Evaluation Board (EVB) with appropriate power supply, RS-232 serial cable, USB cable, antenna and the module. For more details, please refer to the *document* [2].

2.4 Assisted GPS

Supplying aided information, like ephemeris, almanac, rough last position, time, and satellite status, can improve the acquisition sensitivity. L10-C module supports OMA SUPL compliant, but for lack of some testing condition, it is still not be verified by Quectel.

2.5 Protocol

The module supports standard NMEA-0183 protocol and MTK private protocol (PMTK messages) that can be used to provide extended capabilities for many applications. The module is capable of supporting the following NMEA formats: *GGA, GSA, GLL, GSV, RMC, ZDA, and VTG*.

Table 4: The module supports protocol

Protocol	Type
NMEA	Input/output, ASCII, 0183, 3.01
PMTK	Input/output, MTK private protocol

Note: Please refer to document [3] about NMEA standard protocol and MTK private protocol.

3. Application interface

The module is equipped with 28-pin 1.1mm pitch SMT pads that connect to user's application platform. Sub-interfaces included in these pads are described in details in the following chapters:

- Power supply (*refer to Chapter 3.3*)
- UART interfaces (*refer to Chapter 3.7*)
- USB interfaces (*refer to Chapter 3.8*)

Electrical and mechanical characteristics of the SMT pad are specified in *Chapter 5&Chapter 6*.

3.1 Pin description

Table 5: Pin description

Power Supply				
PIN NAME	I/O	DESCRIPTION	DC CHARACTERISTICS	COMMENT
VCC	I	Supply voltage	V _{max} = 4.3V V _{min} =3.0V V _{norm} =3.3V	Supply current for no less than 150mA.
V_BCKP	I	Backup voltage supply	V _{max} =4.3V V _{min} =2.0V V _{norm} =3.3V I _{in} =4uA	Power supply for RTC when VCC is not applied for the system.
VCC_OUT	O	Output voltage	V _{max} = 4.3V V _{min} =3.0V V _{norm} =3.3V I _{max} =20mA	If not used, keep this pin open. This pin is internally connected to VCC.
VCC_RF	O	Output voltage RF section	V _{max} =4.3V V _{min} =3.0V V _{norm} =3.3V I _{max} =50mA	If not used, keep this pin open. Usually supply for external active antenna. VCC_RF≈ VCC-0.1V
V_ANT	I	Antenna bias voltage	V _{max} =5.5V V _{min} =2.8V	If not used, keep this pin open. Using VCC_RF or external voltage source.

Reset				
PIN NAME	I/O	DESCRIPTION	DC CHARACTERISTICS	COMMENT
RESET_N	I	System reset, low level active.	VILmin=-0.3V VILmax=0.5V VIHmin=2.1V VIHmax=2.8V	If not used, keep this pin open. Internally pulled up
General purpose input/output				
PIN NAME	I/O	DESCRIPTION	DC CHARACTERISTICS	COMMENT
EXTINT0	I	External interrupt input	VILmin=-0.3V VILmax=0.8V VIHmin=2.0V VIHmax= 3.6V VOLmin=-0.3V VOLmax=0.4V VOHmin=2.4V VOHmax=2.9 V	If not used, keep this pin open. Internally pulled up.
TIMEPULSE	O	Time pulse	VOLmin=-0.3V VOLmax=0.4V VOHmin=2.4V VOHmax=2.9V	1 pulse per second (1PPS.) Synchronized at rising edge, 100ms pulse width. If not used, keep this pin open.
UART port				
PIN NAME	I/O	DESCRIPTION	DC CHARACTERISTICS	COMMENT
RXD1	I	Receive data	VILmin=-0.3V VILmax=0.8V VIHmin=2.0V VIHmax= 3.6V	Be used to output NMEA and input PMTK private messages
TXD1	O	Transmit data	VOLmin=-0.3V VOLmax=0.4V VOHmin=2.4V VOHmax=2.9V	
USB Port				
PIN NAME	I/O	DESCRIPTION	DC CHARACTERISTICS	COMMENT
VDDUSB	I	Voltage supply for USB port	Vmax=3.6V Vmin=3.0V Vnorm=3.3V	If not used , connect to GND.
USB_DM	I/O	USB data negative	Compliant with USB2.0 specification	If not used, keep this pin open. Compatible with USB with 27 Ohms series resistance.
USB_DP		USB data positive		

RF interface				
PIN NAME	I/O	DESCRIPTION	DC CHARACTERISTICS	COMMENT
RF_IN	I/O	GPS signal input	Impedance of 50Ω	<i>Refer to chapter 4</i>

3.2 Operating modes

The table below briefly summarizes the various operating modes referred to in the following chapters.

Table 6: Overview of operating modes

Mode	Function
Acquisition mode	The module starts to search satellite, determine visible satellites and coarse carrier frequency and code phase of satellite signals. When the acquisition is performed, it switches to tracking mode automatically.
Tracking mode	The module refines acquisition's message, as well as keeps tracking and demodulating the navigation data from the specific satellites.
Standby mode	EXTINT0 pin can be used to make the module enter into standby mode. In this case, the UART port and USB port are not accessible, and the current consumption of the module is also minimal. The module could be woken up by EXTINT0 pin.

3.3 Power supply

The main power supply is fed through the VCC pin. It is important that the system power supply circuitry is able to support the peak power. So the power supply must be able to provide sufficient current up to 150mA.

The circuit design of the power supply strongly depends on the power source where this power is drained. An LDO (Low Dropout Regulator) device, such as Torex (<http://www.torex.co.jp/English>) XC6219B332MR is recommended. For more details of this power supply application, please refer to *document [1]*.

3.4 Turn on and turn off

3.4.1 Turn on

The module can be turned on by two ways which are described in the following chapters:

- Power on reset (*please refer to chapter 3.4.1.1*);
- Via RESET_N pin: restarts module (*please refer to chapter 3.4.1.2*)

3.4.1.1 Power on

A built-in reset controller automatically turns on the module when VCC is supplied.

3.4.1.2 Restart module using the RESET_N pin

L10-C module can be restarted by driving the RESET_N to low level voltage for a certain time and then releasing it. An open drain driver circuit is suggested in application to control the RESET_N. A simple reference circuit is illustrated in Figure 2.

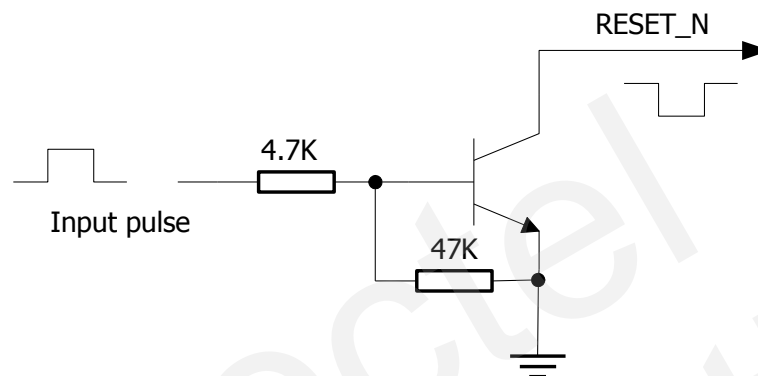


Figure 2: Reference reset circuit using OC circuit

The other way to control the RESET_N is using a button directly. A TVS component needs to be placed nearby the button for ESD protection. While pressing the key, ESD strike may be generate from finger. A reference circuit is illustrated in Figure 3.

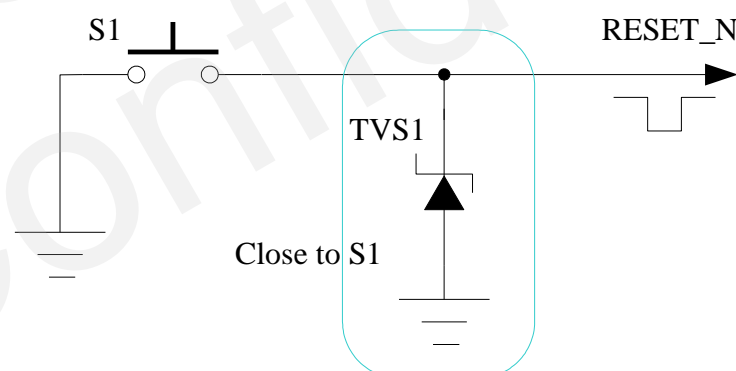


Figure 3: Reference reset circuit using button

The restart timing is illustrated in Figure 4.

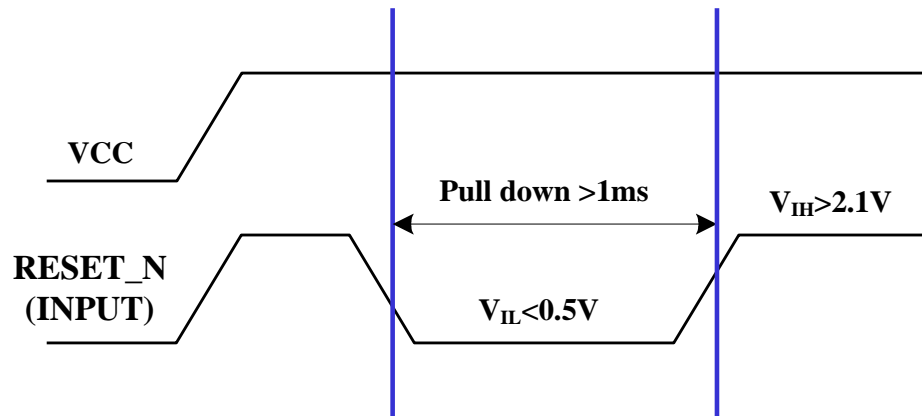


Figure 4: Timing of restart system

3.4.2 Turn off

Shutting down the module's power supply is the only way to turn off the system. For more details of this part application, please refer to *document [1]*.

3.5 Power saving

3.5.1 Enter standby mode

The EXTINT0 pin can be used to drive the module into standby mode. When the EXTINT0 pin is changed from high to low, the module will enter the standby mode. In this case, the UART port and the USB port are not accessible, and the current consumption of the module is also minimal.

Note: When USB interface of the module is being used, the module could not enter standby mode.

3.5.2 Exit from standby mode

When the EXTINT0 pin is changed from low to high, the module will exit from the standby mode.

3.6 RTC backup

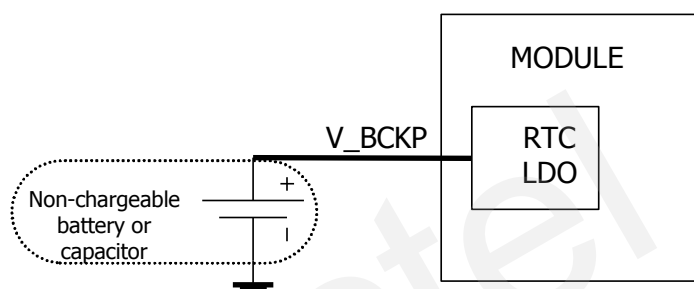
The RTC (Real Time Clock) power supply of module can be directly provided by an external capacitor or battery (rechargeable or non-chargeable) through the V_BCKP pin. It can supply power for backed-up memory which contains all the necessary GPS information for quick start-up and a small amount of user configuration variables.

Table 7: Pin definition of the V_BCKP pin

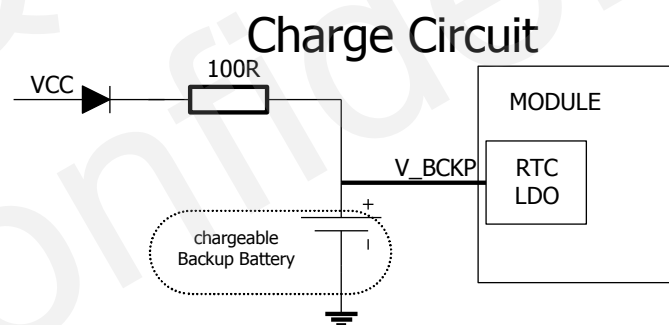
Name	Pin	Function
V_BCKP	11	Backup voltage supply

Note: The V_BCKP couldn't keep open. The V_BCKP pin should be connected to a battery or a capacitor for GPS module hot start and AGPS.

Please refer to the following figure for RTC backup:

**Figure 5: RTC supply from non-chargeable battery or capacitor**

The V_BCKP pin does not implement charging for rechargeable battery. It is necessary to add a charging circuit for rechargeable battery, as shown in the following figure:

**Figure 6: Reference charging circuit for chargeable battery**

- **Coin-type Capacitor backup**

Coin-type Rechargeable Capacitor such as XH414H-IV01E from Seiko can be used.

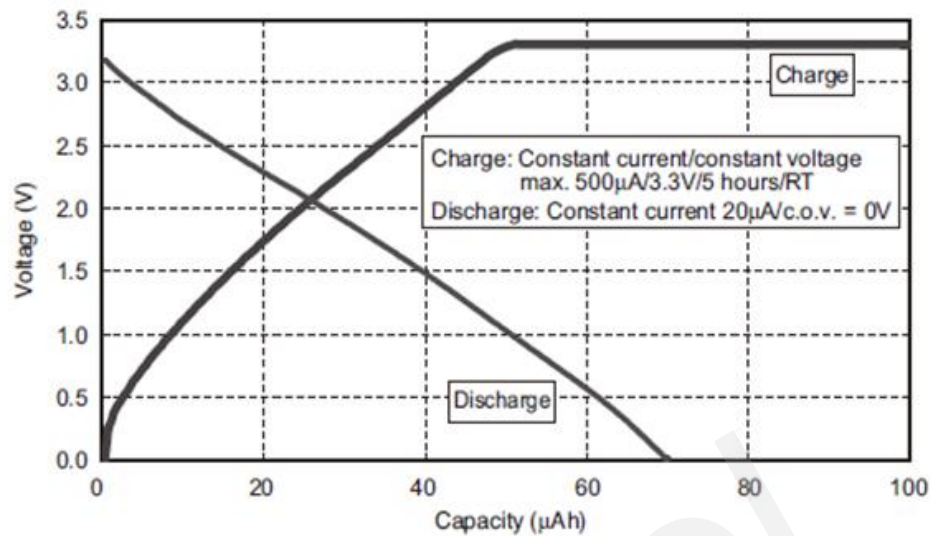


Figure 7: Seiko XH414H-IV01E charge characteristic

3.7 UART interface

UART port is used for the NMEA&PMTK input/output

Table 8: Pin definition of the UART interfaces

Interface	Name	Pin	Function
UART Port	TXD1	3	Transmit data
	RXD1	4	Receive data

UART port:

- TXD1: Send data to the RXD signal line of DTE
- RXD1: Receive data from the TXD signal line of DTE

The module is designed as a DCE (Data Communication Equipment), following the traditional DCE-DTE (Data Terminal Equipment) connection. The module and the client (DTE) are connected through the following signal (shown as Figure 8). It supports data baud-rate from 4800bps to 115200bps.

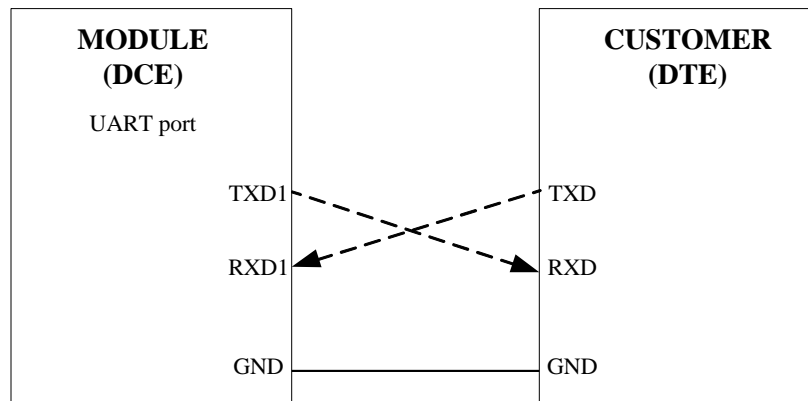


Figure 8: Connection of UART port

This UART port has the following features:

- UART port can be used for firmware upgrade, inputting or outputting NMEA or PMTK private messages.
The default output NMEA type setting is **RMC, VTG, GGA, GSA, GSV, and GLL.**
- UART port supports the following data rates:
4800, 9600, 14400, 19200, 28800, 38400, 57600, 115200
The default setting is 9600bps, 8 bits, no parity bit, 1 stop bit, no hardware flow control.
- Hardware flow control and synchronous operation are not supported.

Note: It is strongly recommended that the UART port is used to output NMEA message to serial port of host in design.

The default setting is 9600bps, 8 bits, no parity bit, 1 stop bit, no hardware flow control

The UART port does not support the RS-232 level but only support the LVTTTL level. If the module's UART port is connected to the UART port of computer, it is necessary to add a voltage level shift circuit between the module and the computer. Please refer to the following figure.

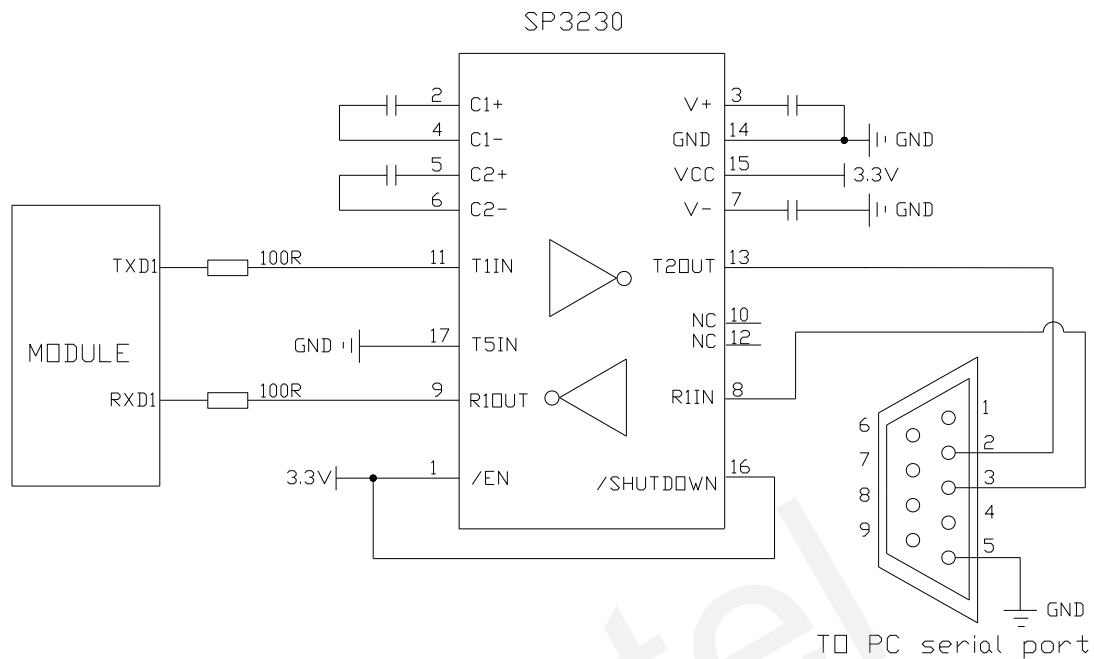


Figure 9: RS-232 level shift circuit

3.8 USB interface

The USB (Universal Serial Bus) port which is compatible with Full-Speed USB 2.0 makes the GPS receiver capable of significantly improving data transmission and receiving rate. This interface is automatically converted to COM port to HOST operating systems and its driver could operate on Windows 98, 2000, XP, and Vista operation system. Customer can update firmware through this port.

The USB port can be used for firmware update, inputting or outputting NMEA or PMTK private messages. It is the same function as serial port.

Plug-and-Play feature provides easier way for customer's data communication with most navigation software. Moreover, flexibility of applications for different USB classes is available.

Table 9: Pin definition of USB interface

Interface	Name	Pin	Function
USB Port	VDDUSB	24	USB power supply
	USB_DM	25	USB data-
	USB_DP	26	USB data+

In order to comply with USB specifications, VDDUSB must be connected to an LDO as shown in Figure 10 when the USB port is used. For more details please refer to *document [1]*.

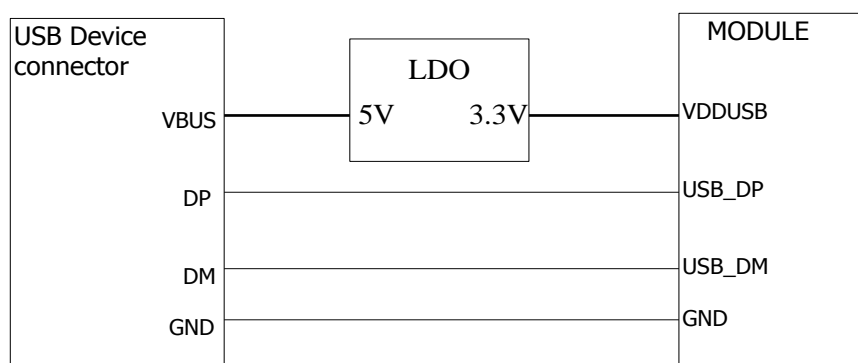


Figure 10: USB interface circuit

Note: The USB interface is not recommended to output NMEA message to USB port of the host, such as ARM processor because the driver of USB may be not reliable. If don't use the USB port, please connect VDDUSB to GND.

3.9 Software upgrade

The UART port and USB port can be used for firmware upgrade, and one of them should be selected.

3.10 EXTINT0

The EXTINT0 pin is an external interrupt input pin. It is an edge trigger interrupt and can be used to wake up the module from the standby mode. When the EXTINT0 pin is changed from high to low, the module will enter into the standby mode. When the EXTINT0 pin is changed from low to high, the module will exit from standby mode.

Table 10: Pin definition of the EXTINT0

Name	Pin	Function
EXTINT0	27	External interrupt input

4. Antenna interface

L10-C module receives L1 band signal from GPS satellites at a nominal frequency of 1575.42MHz. The RF signal is connected to the RF_IN pin. Customer should use a controlled impedance transmission line of 50 Ohm to connect to RF_IN.

4.1 Antenna

L10-C module can be connected to passive or active antenna. The specification of passive antenna and active antenna is listed as Table 11

Table 11: Antenna specification for L10-C module

Antenna type	Specification
Passive antenna	Center frequency: 1575.42 MHz Band Width: >20 MHz Gain: >0 dBi Polarization: RHCP or Linear
Active antenna	Center frequency: 1575.42 MHz Band Width: >5 MHz Minimum gain: 15-20dBi(compensate signal loss in RF cable) Maximum noise figure: 1.5dB Maximum gain: 50dBi Polarization: RHCP or Linear

4.2 Antenna supply

4.2.1 Passive antenna

Passive antenna does not require a DC bias voltage and can be connected to RF_IN pin directly. V_ANT can be connected to GND. It is always beneficial to reserve a passive matching network between the antenna and the RF_IN port of the module. Figure 11 is the reference design.

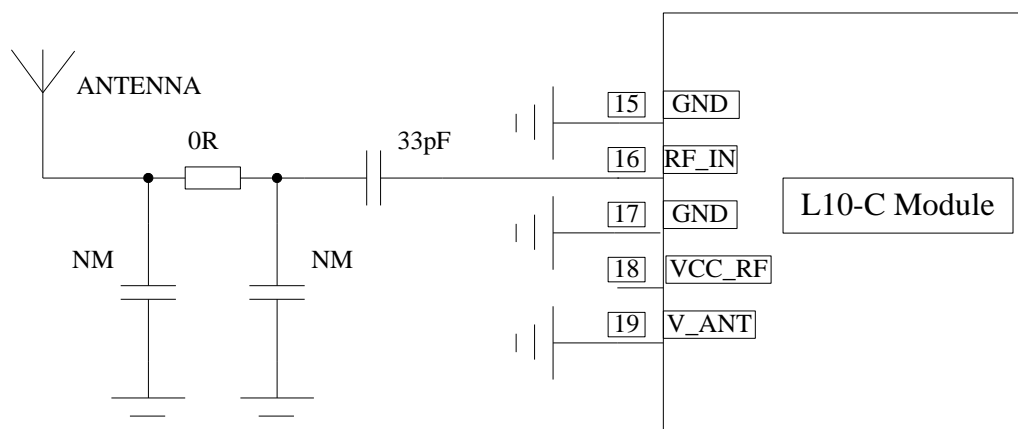


Figure 11: Reference design for passive antenna

4.2.2 Active antenna

Active antenna has an integrated low-noise amplifier which could be connected to RF_IN directly. If an active antenna is connected to RF_IN, the integrated low-noise amplifier of the antenna needs to be supplied with the correct voltage through pin V_ANT. Usually, the supply voltage is fed to the antenna through the coaxial RF cable. An active antenna consumes current at 5~20mA. The inductor inside the module can separate the RF signal from the V_ANT pin and route the bias supply to the active antenna. The block diagram of the supply part for active antenna is shown in Figure 12.

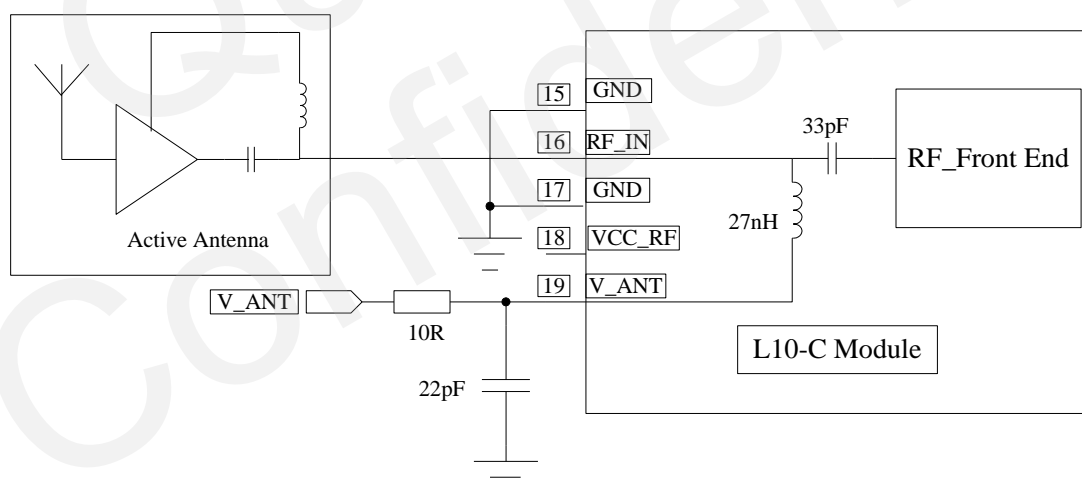


Figure 12: Active antenna biasing

If the VCC_RF voltage is suitable for powering the active antenna, pin VCC_RF could be directly connected to pin V_ANT. A reference circuit is shown in Figure 13.

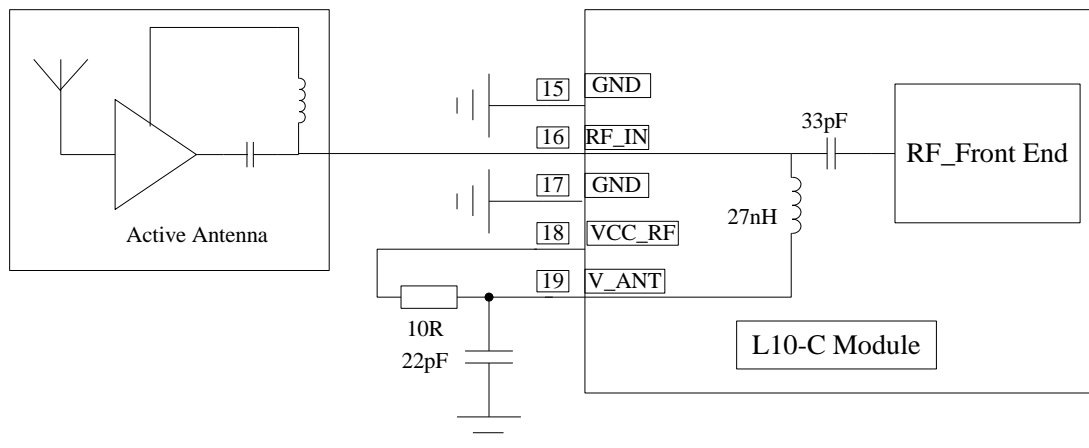


Figure 13: Active antenna using VCC_RF as power supply

Note: When the active antenna uses VCC_RF as power supply and the module enter standby mode, the current consumption of the module is minimal, but the active antenna power supply can not be cut off, so the active antenna will consume current in standby mode.

If the VCC_RF voltage does not meet the requirement for powering the active antenna, an external LDO could be used. The output of the external LDO can be connected to pin V_ANT. A reference circuit is shown in Figure 14.

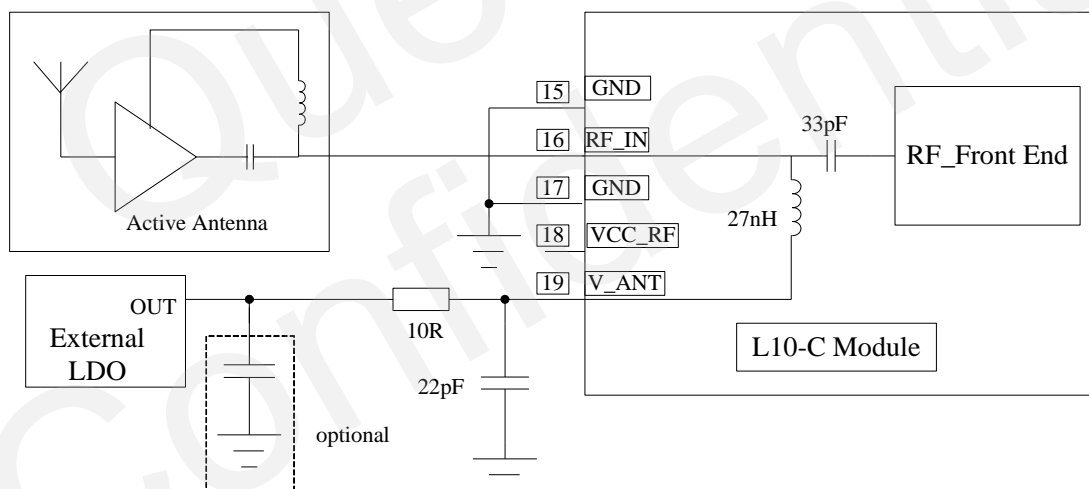


Figure 14: Active antenna with external LDO

5. Electrical, reliability and radio characteristics

5.1 PIN assignment of the module

Table 12: L10-C pin assignment

PIN NO.	PIN NAME	I/O		PIN NO.	PIN NAME	I/O
1	RESERVED			15	GND	
2	RESERVED			16	RF_IN	I
3	TXD1	O		17	GND	
4	RXD1	I		18	VCC_RF	O
5	RESERVED			19	V_ANT	I
6	VCC	I		20	RESERVED	
7	GND			21	RESERVED	
8	VCC_OUT	O		22	RESERVED	
9	RESERVED			23	RESERVED	
10	RESET_N	I		24	VDDUSB	I
11	V_BCKP	I		25	USB_DM	I/O
12	RESERVED			26	USB_DP	I/O
13	GND			27	EXTINT0	I
14	GND			28	TIMEPULSE	O

Note: Please keep all reserved pins open.

5.2 Absolute maximum ratings

Absolute maximum rating for power supply and voltage on digital pins of module are listed in Table 13.

Table 13: Absolute maximum ratings

Parameter	Min	Max	Unit
Power supply voltage (VCC)	-0.3	4.3	V
Backup battery voltage (V_BCKP)	-0.3	4.3	V
USB supply voltage (VDDUSB)	-0.3	3.6	V
Input voltage at digital pins	-0.5	3.6	V
	-0.5	3.6	V
VCC_RF output current (Ivccrf)		50	mA
Input power at RF_IN (Prfin)		0	dBm
Antenna bias voltage (V_ANT)	0	6	V
Storage temperature	-45	125	°C

Note: Stressing the device beyond the “Absolute Maximum Ratings” may cause permanent damage. These are stress ratings only. The product is not protected against over voltage or reversed voltage. If necessary, voltage spikes exceeding the power supply voltage specification, given in table above, must be limited to values within the specified boundaries by using appropriate protection diodes.

5.3 Operating conditions

Table 14: The module power supply ratings

Parameter	Description	Conditions	Min	Typ	Max	Unit
VCC	Supply voltage	Voltage must stay within the min/max values, including voltage drop, ripple, and spikes.	3.0	3.3	4.3	V
I _{VCCP} [*]	Peak supply current	VCC=3.3V			150	mA
V_BCKP	Backup voltage supply		2.0	3.3	4.3	V
I _{BCKP}	Backup battery current	V_BCKP=3.3V		4		uA
V_ANT	Antenna bias voltage		2.8		5.5	V
V _{ANT_DROP}	Antenna bias voltage drop				0.1	V

Parameter	Description	Conditions	Min	Typ	Max	Unit
I _{ANT}	V _{ANT} supply current	V _{ANT} =3.3V			100	mA
VDDUSB	USB supply voltage		3.0	3.3	3.6	V
VCC_RF	Output voltage RF section				VCC -0.1	V
I _{VCC_RF}	VCC_RF output current				50	mA
T _{OPR}	Normal Operating temperature		-40	25	85	°C

** Use this figure to determine the maximum current capability of power supply.*

Note: Operation beyond the "Operating Conditions" is not recommended and extended exposure beyond the "Operating Conditions" may affect device reliability.

5.4 Current consumption

The values of current consumption are shown in Table 15.

Table 15: The module current consumption (passive antenna)

Parameter	Condition	Min	Typ	Max	Unit
Icc Acquisition	Passive antenna@-130dBm		43		mA
Icc Tracking	For Cold Start, 10 minutes after First Fix. For Hot Start, 15 seconds after First Fix with passive antenna.		35		mA
Icc Standby	EXTINT0 pin is changed from high to low with passive antenna.		2		mA

5.5 Electro-static discharge

Although the module is fully protected against ESD strike, ESD protection precautions should still be emphasized. Proper ESD handling and packaging procedures must be applied throughout the processing, handling and operation of any application.

The ESD bearing capability of the module is listed in Table 16.

Table 16: The ESD endurance table (Temperature: 25°C, Humidity: 45 %)

Pin	Contact discharge	Air discharge
Antenna port	±5KV	±10KV
VCC,GND	±4KV	±8KV
Others	±4KV	±8KV

5.6 Reliability test

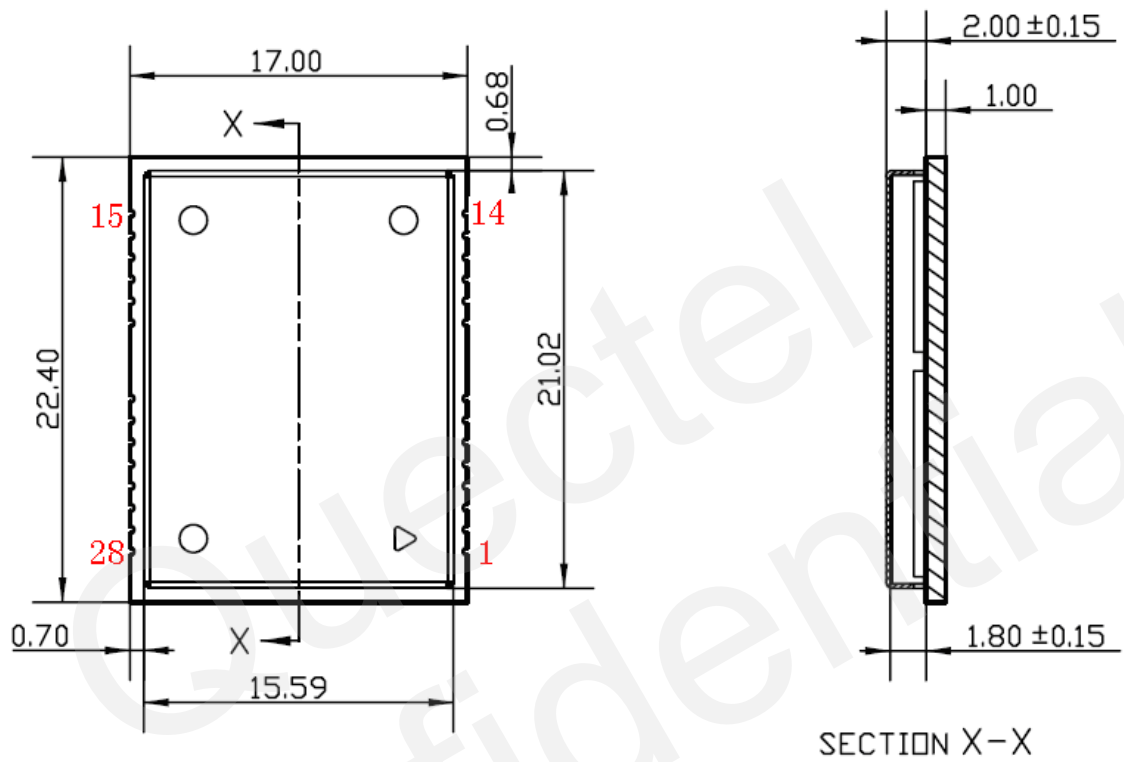
Table 17: Reliability test

Test term	Condition	Standard
Thermal shock	-30 °C...+80 °C, 144 cycles	GB/T 2423.22-2002 Test Na IEC 68-2-14 Na
Damp heat, cyclic	+55 °C; >90% Rh 6 cycles for 144 hours	IEC 68-2-30 Db Test
Vibration shock	5~20Hz,0.96m ² /s ³ ;20~500Hz,0.96m ² /s ³ -3dB/oct, 1hour/axis; no function	2423.13-1997 Test Fdb IEC 68-2-36 Fdb Test
Heat test	85 °C, 2 hours, Operational	GB/T 2423.1-2001 Ab IEC 68-2-1 Test
Cold test	-40 °C, 2 hours, Operational	GB/T 2423.1-2001 Ab IEC 68-2-1 Test
Heat soak	90 °C, 72 hours, Non-Operational	GB/T 2423.2-2001 Bb IEC 68-2-2 Test B
Cold soak	-45 °C, 72 hours, Non-Operational	GB/T 2423.1-2001 A IEC 68-2-1 Test

6. Mechanics

This chapter describes the mechanical dimensions of the module.

6.1 Mechanical dimensions of the module



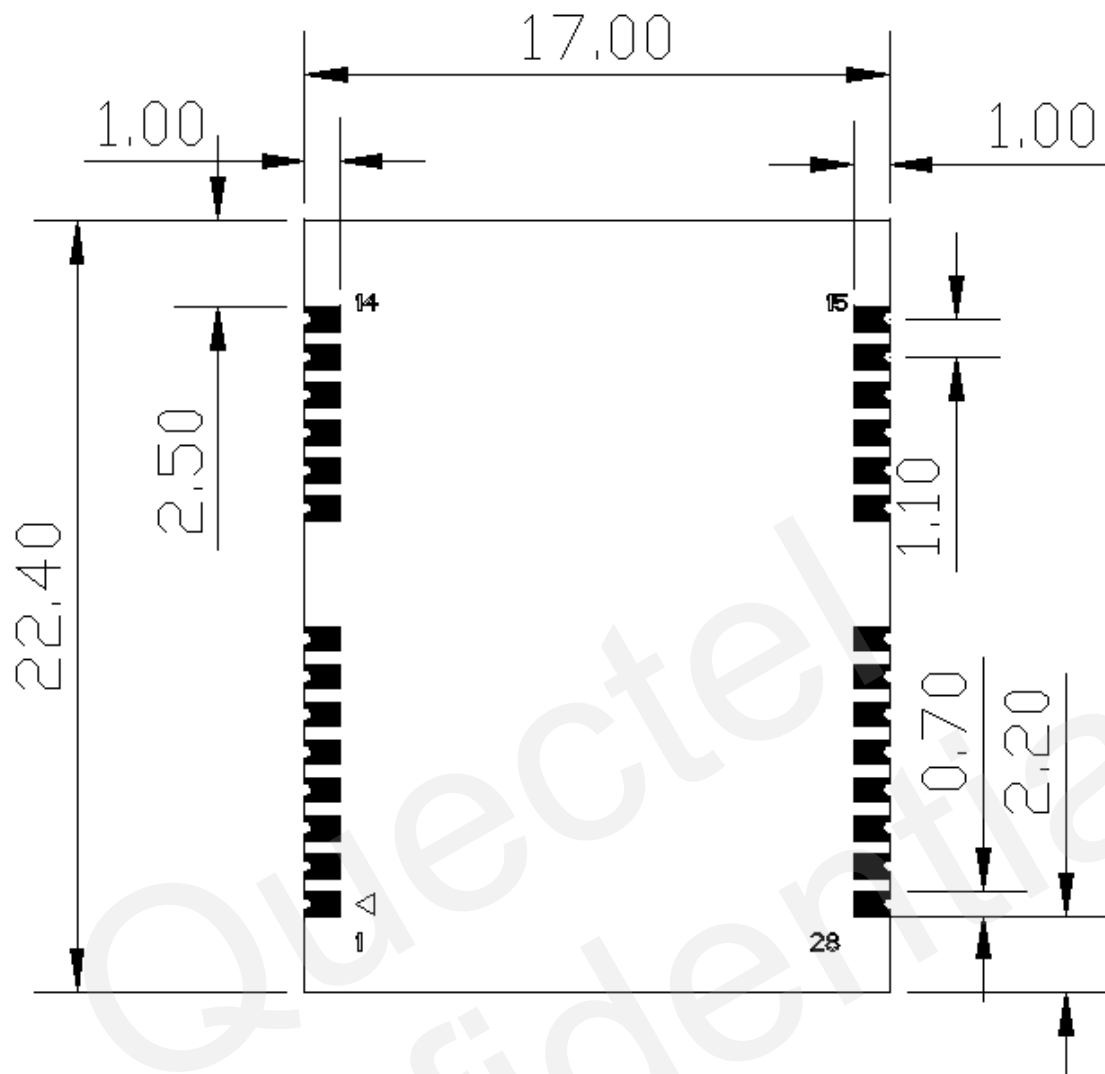


Figure 16: L10-C Bottom dimensions (Unit:mm)

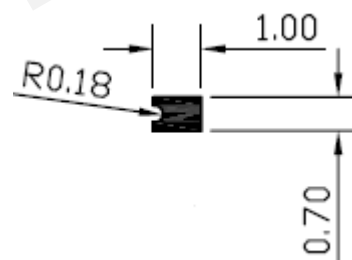


Figure 17: PAD Bottom dimensions (Unit:mm)

6.2 Footprint of recommendation

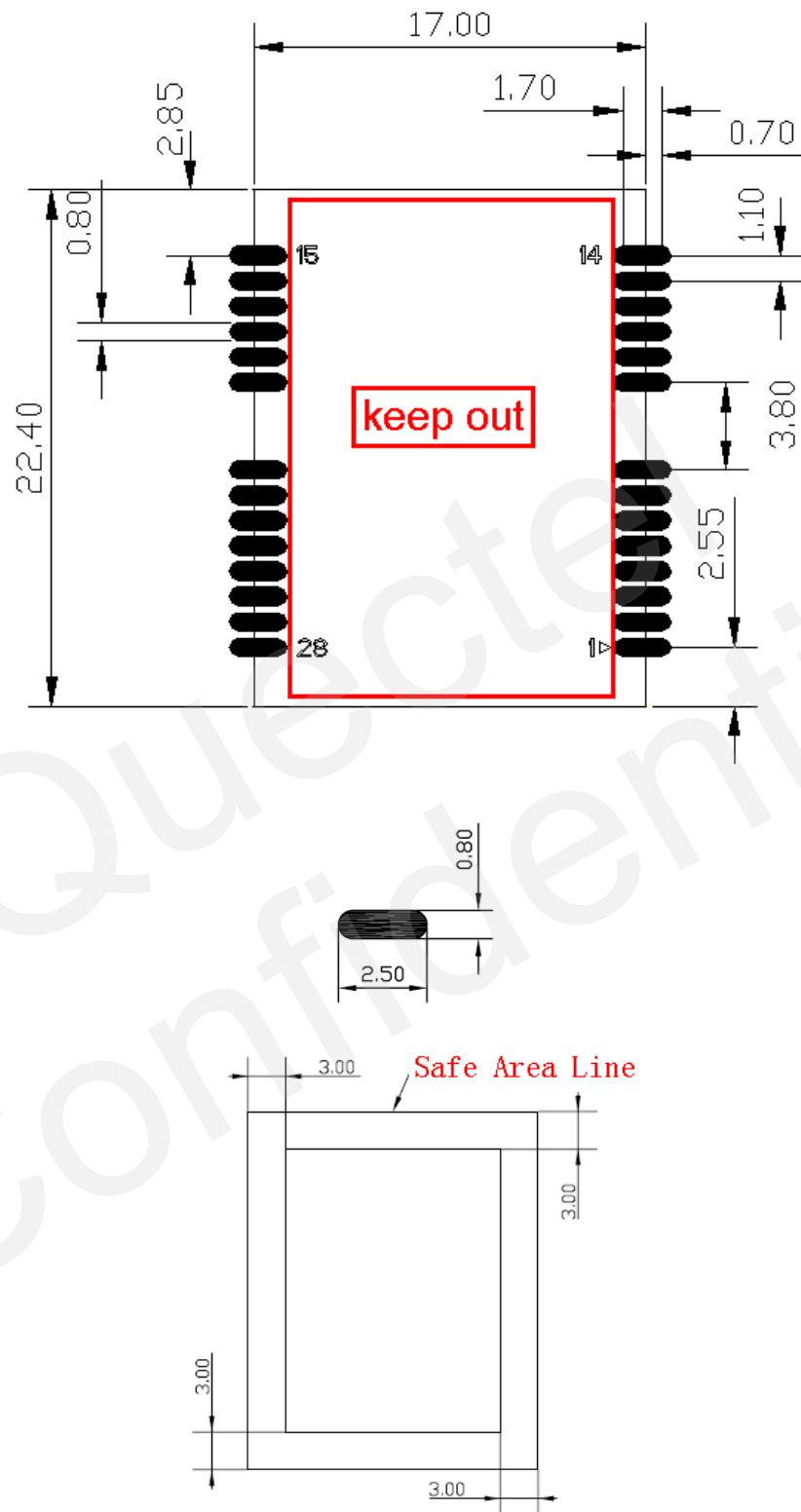


Figure 18: Footprint of recommendation (Unit: mm)

Note1: Keep out on the host board below the module and the keep-out area should be covered by solder mask and top silk layer for isolation between the top layer of host board and the bottom layer of the module.

Note2: For easy maintenance of this module and accessing to these pads, please keep a distance no less than 3mm between the module and other components in host board.

6.3 Top view of the module



Figure 19: Top view of the module

6.4 Bottom view of the module

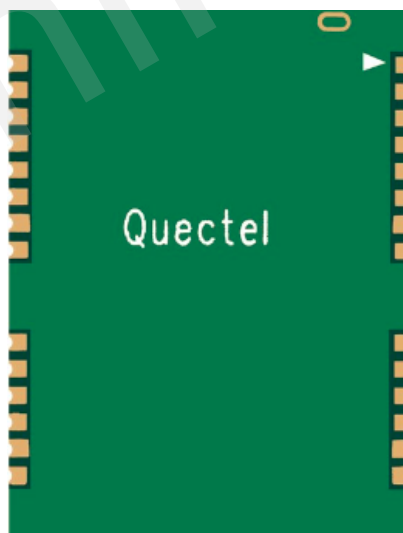


Figure 20: Bottom view of the module

QUECTEL



Shanghai Quectel Wireless Solutions Co., Ltd.

Room 501 Building 13, No.99, TianZhou Road, Shanghai, China 201103

Tel: +86 21 5108 6236

Mail: info@quectel.com